



Acknowledgements



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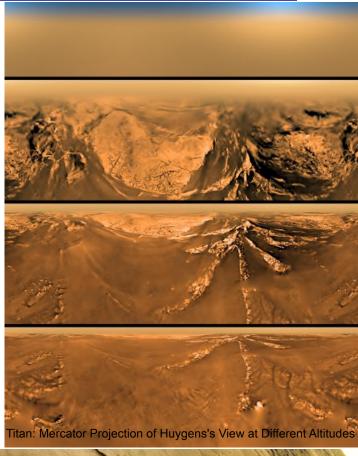
- Dr Ajay Misra, Program Executive for the RPS Program at NASA HQ;
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- Extreme Environments
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- Conclusions

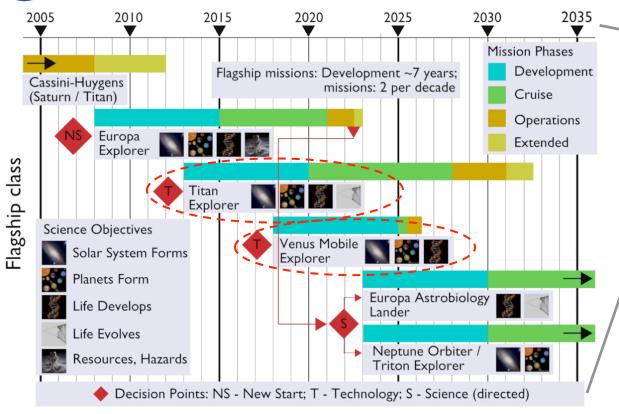




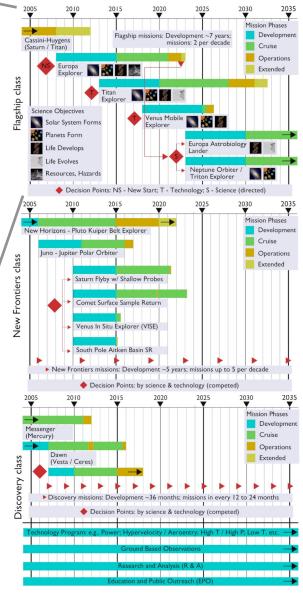


Introduction





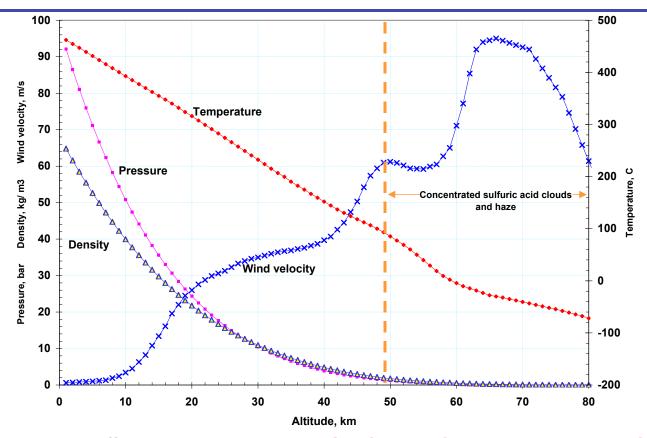
- The **2006 SSE Roadmap Update** is currently under way
- The Roadmap identifies proposed long-lived
 Flagship class missions to both Titan and Venus





Extreme Environments – 1: Venus (High T,p)





- Greenhouse effect results in VERY HIGH SURFACE TEMPERATURES
- Average surface temperature:

~ 460 to 480°C

• Average **pressure** on the surface:

~ 92 bars

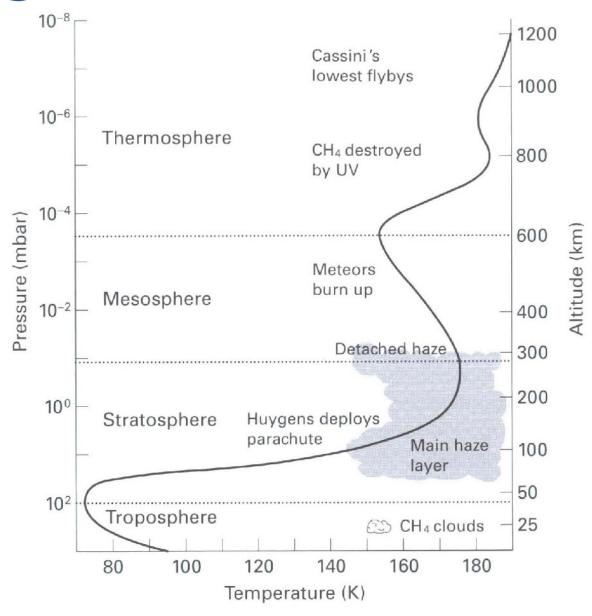
- Cloud layer composed of aqueous sulfuric acid droplets at ~45 to ~70 km attitude
- Venus atmosphere is mainly CO₂ (96.5%) and N₂ (3.5%) with:
 - small amounts of noble gases (He, Ne, Ar, Kr, Xe)
 - small amount of reactive trace gases (SO₂, H₂O, CO, OCS, H₂S, HCl, SO, HF ...)
- Zonal winds: at near surface ~ 1 m/s; at 60 km altitude ~ 60+ m/s



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Extreme Environments – 2: Titan (Low T)





- The temperature at the surface is VERY COLD: about -178°C
- Pressure is ~1.5 bars
- ~2-10% methane clouds and about 90% Nitrogen



Ref: http://www.atmo.arizona.edu/students/courselinks/spring05/atmo336s2/TitanTemperatureProfile.jpg

Pre-decisional – for discussion purposes only



Venus Mobile Explorer Concept



Scientific Objectives:

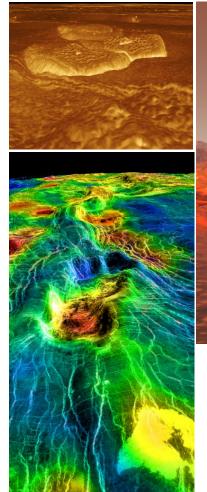
- Composition and isotopic measurements of surface and atmosphere
- Near IR descent images
- Acquire and characterize a core sample at multiple sites.
- Demonstrate key technologies for VSSR

Exploration Metrics:

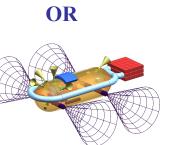
- Operate in Venus surface environment for 90 days+
- Range and altitude if aerial vehicle TBD
- Range across surface if rover TBD

Mission & LV Class:

- LV: Delta-IV-H / Atlas V







Science Payload:

- Neutral mass spectrometer with enrichment cell.
- Instruments to measure elements and mineralogy of surface materials.
- Imaging microscope

Technology & Heritage:.

- Sample acquisition and handling in Venus environment
- Thermal control technology
- Long duration operation in situ

Mission Technology Studies:

- Decadal Survey 2002 none.
- Technology studies at JPL for definition of advanced RPS systems, 2005
- Extreme Environments Technologies at JPL, FY06.

Flagship Class

Earliest Launch Opportunity: Technology Readiness: 2022 Programmatic Slot: 2025



High Temperature Mitigation – Mission Architecture Options



OPTION 1

Use conventional components and provide survivability solely through thermal control

Impractical or not possible for some missions

OPTION2.

Use only components capable of surviving in extreme environment

Prohibitively expensive for many technologies





Hybrid Solution: 1+2

Use a <u>combination of advanced thermal control and components</u> able to operate at extreme HT/high pressure environments

The <u>hybrid</u> option offers the <u>best solution</u> for optimizing mission architecture; This requires <u>power + active cooling</u>



Titan Explorer (Orbiter & In Situ) Concept



Scientific Objectives:

- Map Titan with high resolution radar.
- Characterize prebiotic chemistry and search for past life.
- Characterize surface and subsurface materials.

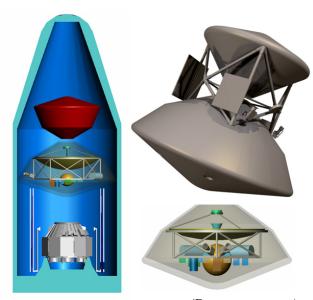
Exploration Metrics:

- Orbiter with lifetime of about two years
- Operate on Titan for at least 90 days – aerial mobility, with Montgolfier & surface sample
- Proximity communications from orbiter to Titan Explorer

Mission & LV Class:

- Flagship Class
- LV TBD





(Design concept)

Science Payload:

- Imaging radar and other remote sensing on orbiter.
- Remote sensing and in situ instruments from Titan Explorer

Technology & Heritage:

- Aerocapture for Titan orbit insertion.
- RPS power on orbiter and in situ vehicle.
- · Aerial mobility with sampling

Mission Technology Studies:

- Decadal Survey 2002
- Two Vision Mission studies in 2005
- Technology studies in: In Space Propulsion, Low Temperature Materials, and Autonomy.
- Titan Explorer JPL Study in 2006

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General Purpose Heat Source Module (GPHS)



Building Block of Radioisotope Power Systems

Module Mass:

- 1.6 kg per GPHS module
- Includes 0.6 kg of Pu²³⁸O₂ fuel

Dimensions:

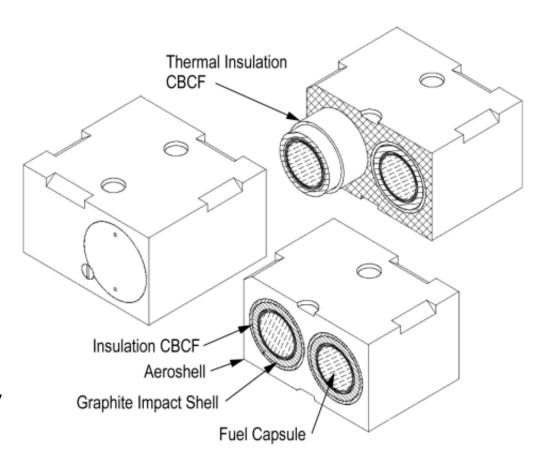
9.96 x 9.32 x 5.82 cm including

Power:

- ~250 W_{th} (BOM) total
- ~62.5 W_{th} per fuel capsule

Operating Temperature:

 Iridium clad operation 1150K, and 1600K, to maintain ductility and limit grain growth



Step-2 Enhanced GPHS Module



Advanced Radioisotope Power Systems



Multi-Mission Radioisotope Thermoelectric Generator (MMRTG) would have these characteristics

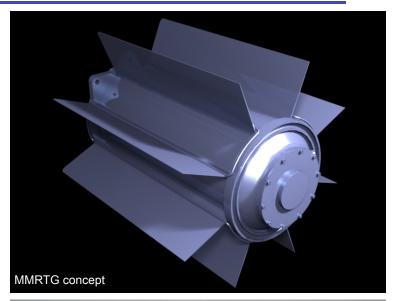
- 166 cm x W64 cm x H64 cm
- Uses 8 GPHS modules (2000Wt)
- Generates ~125 We (BOM)
- Mass ~43 kg
- Specific power ~2.3 We/kg

Stirling Radioisotope Generator (SRG) would have these characteristics

- 1 104 cm x W29 cm x H38 cm
- Uses 2 GPHS modules (500Wt)
- Generates ~116 We (BOM)
- Mass ~34 kg
- Specific power ~3 W/kg

RPSs for Titan and Venus would have to be modified for the environment

- Titan: MMRTG fins would be adjusted for the low temperature, to achieve the required heat rejection rate
- Venus: requires NEW DEVELOPMENT to address the environment; a special Stirling Generator with active cooling might provide a good development path





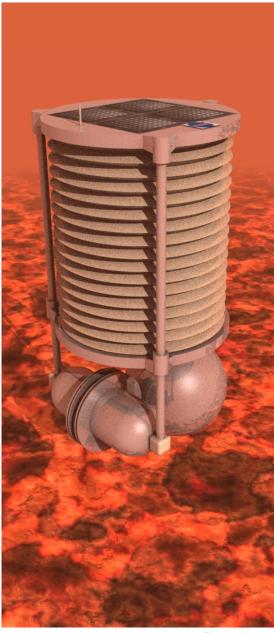




RPS Requirements for the Proposed Venus Mobile Explorer Mission



- The proposed VME spacecraft would operate near the surface of Venus:
 - It would operate continuously at the surface and in the lower atmosphere for many months
 - The RPS would need to tolerate the 480°C and 90 bars extreme environment
 - This would require properly sized heat rejection system and pressure vessel
 - The RPS would need to tolerate the highly corrosive supercritical carbon dioxide environment
 - This would require a suitable coating
 - Russian landers used enamel coating;
 - Kepton coating of US probes failed: 12.5 km anomaly
- Power system would need to provide both power AND active cooling to the instruments
 - Generator would produce electricity by converting radioisotopic heat,
 - similar to outer planets missions, but more difficult.
 - This RPS would enable the **hybrid thermal management** system, where a mechanical refrigerator cools non hardened payload elements, for example microprocessor and imaging sensor
- **High specific power** (this might be a challenging due to the environment)
 - An air mobility system would require a light power source due to limited lifting capacity
 - A specially developed Stirling Radioisotope Generator with active cooling could point to an suitable RPS development direction





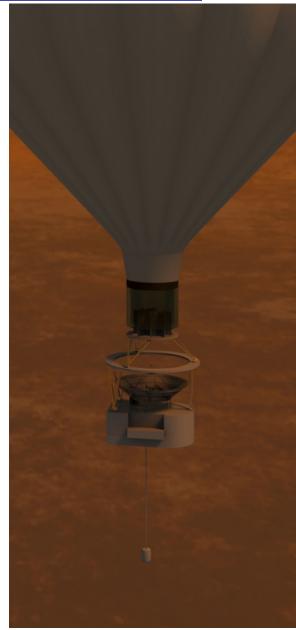
RPS Requirements for the Proposed <u>Titan Explorer</u> Mission



- Hot air balloons, by definition, require heat, therefore,
 - This concept would not only utilize the electric power from the RPS, but also the thermal power (excess heat) to keep the balloon afloat
 - Therefore, plutonium reduction for this this concept is not considered to be a key driver
 - However, improved conversion efficiency could provide more power for the same amount of Pu-238, enabling higher telecom data rates, more instrument operations, etc.
- RPS thermal design would need to be adjusted for the cold Titan environments
 - Fin size would need to be adjusted to achieve the required heat rejection, and the temperature drop across the thermoelectrics
- MMRTG could be considered with the above fin modifications
- Number of RPSs:

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- A single MMRTG could work
- Two MMRTGs would provide more power, and more thermal power, which would reduce the size of the hot air balloon (Montgolfier), countering the mass penalty of the additional power source
- Two MMRTGs would possibly require special accommodation during cruise, and operations, to provide good heat rejection





Operation Through All Mission Phases



- RPS generates heat continuously (radioisotope decay)
- This would need to be mitigated through all mission phases

Earth storage phase;

- Earth environment; convection + conduction + radiation
- Launch (and pre-launch integration) phase;
 - Earth environment; convection + conduction + radiation

Cruise phase;

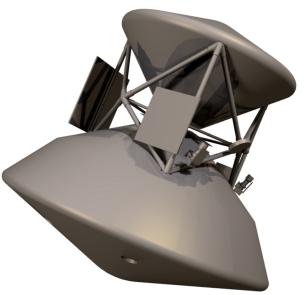
 RPS enclosed inside the aeroshell; would require active cooling and heat rejection to space through external radiators; forced convection fluid loop + conduction + radiation

Entry, Descent, and Landing (EDL) phase;

 Short period, but active cooling disabled, limited heat transfer; radiation and conduction only during entry; aeroshell would need to absorb excess heat

In situ operations phase (Titan/Venus);

 Planetary atmosphere; RPS design would need to address extreme environment; heat rejection system is specific to environment



Back-to-back Titan aeroshell concept

Venus mission environment:

- Hot inside aeroshell during cruise
- Very **hot operational** environment

Titan mission environment:

- Hot inside aeroshell during cruise
- Extremely cold during operations



Conclusions



- The extreme environments of Titan and Venus introduce many technical challenges:
 - at Titan: low temperature
 - at Venus: high temperature, high pressure, corrosion
- Long lived Flagship class in situ missions referenced in this study require reliable internal power sources, such as RPSs
- RPSs would require modifications to mitigate these extreme environments, but
 - a Titan mission could use existing designs, such as an MMRTG
 - A Venus mission would require a new RPS development;
 providing both power and active cooling to the spacecraft
- RPS technology is considered enabling for these proposed missions





The End



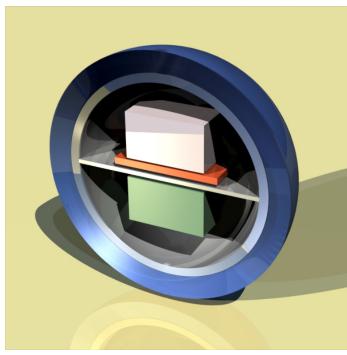


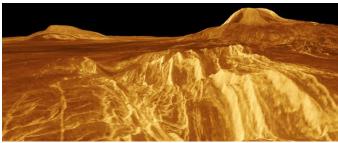
Backup slides



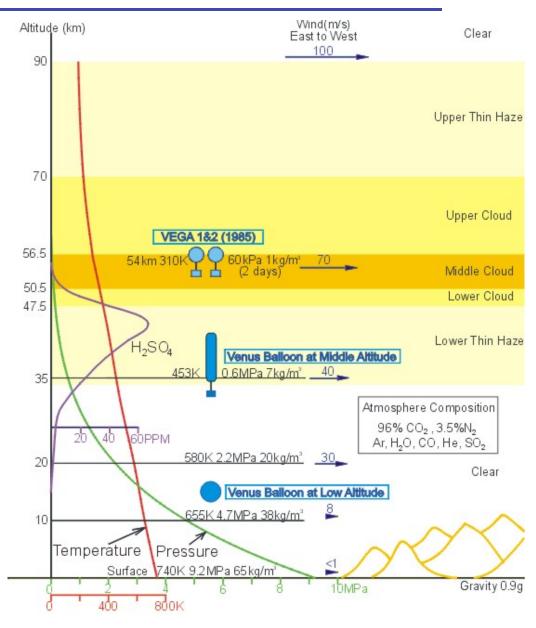
Venus Environment Backup







Ref:
N.Yajima, N.Izutsu, H.Honda, K.Goto and T.Imamura (ISAS)
N.Tomita and K.Akazawa (Musashi Institute of Technology Univ.)
"Feasibility and Applicability of Planetary Balloons,"
Website: www.isas.ac.jp/home/ Sci Bal/engplanetary.html





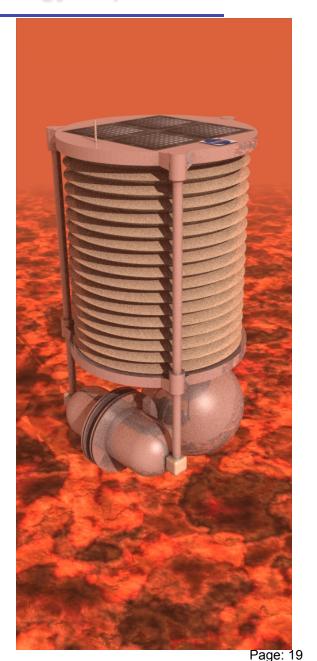
Venus Mobile Explorer: Summary of Technology Capabilities



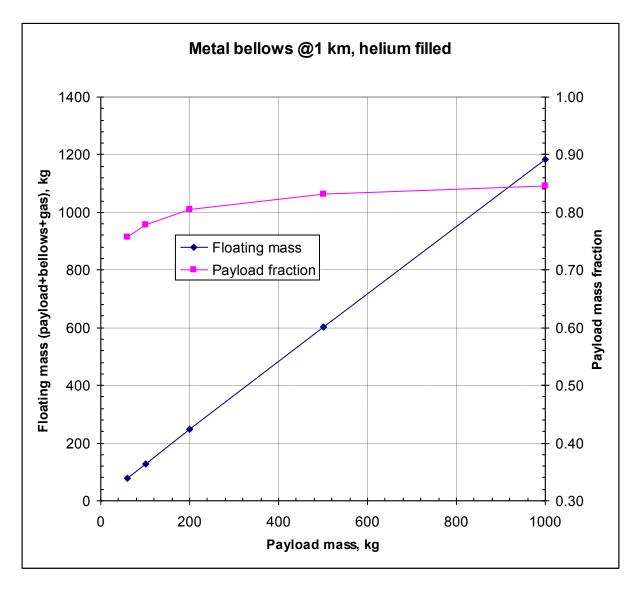
- **Technologies for Extreme Environments**
- Protection against high temperatures and pressures
- Electronics for high temperature operation
- Power only radioisotope power practical
- Active Thermal Control at Venus surface
- Mobility aerial and surface directional control
- Sample Acquisition and handling
- Science Instruments remote sensing and in situ analysis

Many of these technologies can also enable **network** missions including:

- Venus Surface Seismic Network
- Venus Lower Atmosphere Balloon Network



Venus Surface Explorer – Performance Metrics for Metal Bellows Mobility System





Metal bellows – actual picture